

### Sebert Trillingstechniek B.V.



Report: M25.001-P25.001 One Display Solution Date 26 March 2025



## MIL-STD 810/AECTP 400 Random Vibration and Terminal Peak Sawtooth Shock Tests on a PSM-P86RV1



# ISO/IEC 17025 Accredited and ISTA® Certified Testing Laboratory

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**Client** One Display Solution Tjalk 1 e 2411NZ Bodegraven The Netherlands

#### **Contact Person**

Mr. S. W. van Tongeren

Order conformation One Display Solution Purchase Order Number ODS20250046

**Present at the tests** Mr. S. W. van Tongeren of One Display Solution was partially present

S2T Quotation Q25.001

Certificate number C25.001-P25.001 One Display Solution

**Tester / Author** Mr. A. Starz Mr. R. Morris

**Technically approved by** Mr. M.J.H. Magendans

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### 1. Introduction

Under contract of One Display Solution at Bodegraven in The Netherlands, AECTP 400 random vibration and terminal saw tooth shock tests have been carried out on PSM-P86RV1 unit. The tests were carried out on 17 to 20 March 2025. All dynamic tests (for example impact and vibration tests) have been carried out under ISO 17025 accreditation and all static tests (for example the ambient test registrations) are not carried out under accreditation. The fixation of the test item to the test equipment has been made by securing the flat metal base of the shock damper base inside a transport frame directly onto the test surface. Transport wheels were removed to improve the transfer of test energy through the test item and create a worst case transportation scenario.

One Display Solution will carry out the final inspection after the complete test sequence. The purpose of the tests is to determine if the test item meets the mechanical stress requirements. In accordance with One Display Solution no acceptation criteria were defined and no preconditioning was carried out. The test results in this report will be related to the tested test item only.

#### 2. Test procedure and equipment

#### 2.1. General

One test item has been used for the tests, see Table 1 for the details of the test item. The test item which was delivered on 17 March 2025 was checked before starting the test for visual damage and no deviations were found.

Product name*	PSM-P86RV1
Product number / SN*	PSM-P86RV1 / ODSPSM2025001
Monitor model / SN*	PHL-86BDL4511D / AU0A2351003926
Decoder model / SN*	VUWALL PAK40-3 / P-11002734
Actuators model / SN*	OKIN-MEGAMAT20MODIFIED / 10032025
Dimensions [LxWxH]	196 x 181 x 96 cm (including test frame)
Weight	264 kg (including test frame)
Figure	#1 #2

Table 1: Test item #1

\*IFC (Information from Customer)

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### 2.2. Test requirements and Test Plan

The following tables (Test A - D) present the test specifications. See Table 2 for the test plan.

Test standard	AECTP 400 (2019) method 401 – Material Transported by Sea			
Normative document	MIL-STD 810H			
Profile				
Fig. A-6 Frequency/amplitude Break points	Acceleration Power Spectral Density Acceleration Power Spectral Density 000000 1 1 1 1 1 1 1 1 1 1 1 1 1	10 100 1000 Frequency (Hz)		
Cross motion	Is not required in specification and therefore will not be measured			
Degrees of Freedom	≥ 120 DOF			
No spectral lines	$\geq$ 200 lines (or first frequency line is at 0,5 of F <sub>1</sub> )			
Test duration	60 minutes (≈ 3 months sea). Total 3 hours (≈ 9 months sea)			
Direction	X, Y and Z			
Functional test	No			
Control strategy	Multi point weighted average control (When a multi point strategy is not possible, a single control point shall be used)			
Remark	This test will be carried out under accreditation			

Test A: Sea Random vibration test in all direction

\*Max pitch and roll moment 19.500Nm and Max Yaw moment 250Nm

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Test standard	AECTP 400 (2019) method 401 – Material Transported by Rail			
Normative document	MIL-STD 810H			
Profile	$f_1 =  PSDf_1 =  f_a = 5Hz$ $PSDf_a, f_b = 0,005 \text{ g}^2/\text{Hz}$ $f_b = 100\text{Hz}$ $G_{rms}$ value = 0.69 (displacement 5.4 mm pp)			
Fig. A-5 Frequency/amplitude Break points	Acceleration Power Spectral Density (g <sup>2</sup> /Hz) 0 00000 00000 1	10 100 1000 Frequency (Hz)		
Cross motion	Is not required in specification and therefore will not be measured			
Degrees of Freedom	≥ 120 DOF			
No spectral lines	$\geq$ 200 lines (or first frequency line is at 0,5 of F <sub>1</sub> )			
Test duration	60 minutes (≈ 10.000km). Total 3 hours (≈ 30.000km)			
Direction	X, Y and Z			
Functional test	No			
Control strategy	Multi point weighted average control (When a multi point strategy is not possible, a single control point shall be used)			
Remark	This test will be ca	arried out under accreditation		

### Test B: Rail Random vibration test in all direction

\*Max pitch and roll moment 19.500Nm and Max Yaw moment 250Nm

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#### Test C: Common carrier random vibration test (in all direction)

Test standard	AECTP 400 (2019) method 401 – Common Carrier			
Normative document	MIL-STD 810H			
Profile				
Fig. A-4 Frequency/amplitude Break points	0.1000 0.0100 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 1	10 100 100 Frequency (Hz)		
Cross motion	Is not required in specification and therefore will not be measured			
Degrees of Freedom	≥ 120 DOF			
No spectral lines	$\geq$ 200 lines (or first frequency line is at 0,5 of F <sub>1</sub> )			
Test duration	60 minutes (≈ 1600km). Total 3 hours (≈ 4800km)			
Direction	X, Y and Z			
Functional test	No			
Control strategy	Multi point weighted average control (When a multi point strategy is not possible, a single control point shall be used)			
Remark	This test will be carried out under accreditation			
*Max pitch and roll moment 19.500Nm and Max Yaw moment 250Nm				

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Test D: Transport Shock Test

Test standard	AECTP 400 (2019) method 403 – Shock – Procedure II – Transport Shock Test			
Normative document	MIL-STD 810H			
Pulse shape	Terminal Peak Sawtooth			
Profile*	On Road (5000 km)4Off Road (1000 km)4Terminal Peak Sawtooth Pulse Duration: 11 msTerminal Peak Sawtooth Pulse Duration: 5 msAmplitudeNumber of ShocksAmplitude5.14210.26.42112.87.6315.2			
Figure 3 Pulse Configuration and Tolerance Limits	$\begin{array}{ c c c } \hline & & & & & \\ \hline & & & & \\ \hline & & & & \\ \hline & & & &$			
Pre/post- pulse height	Max 15%			
Impact velocity	10 seconds per impact			
Number of impacts	2x 66 impacts per direction (total 132 impacts)			
Filter	Must be calculated			
SRS	Yes			
Direction	X+/-, Y+/- and Z+/-			
Functional test	No			
Control strategy	Multi point weighted average control (When a multi point strategy is not possible, a single control point shall be used)			
Remark	This test will be carried out under accreditation			

\*Max pitch and roll moment 19.500Nm and Max Yaw moment 250Nm

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Table 2: Test plan

Step	Test	Direction	
1	А	Horizontal transversal (X)	
2	В	Horizontal transversal (X)	
3	А	Vertical (Z)	
4	В	Vertical (Z)	
5	С	Vertical (Z)	
6	D	D Vertical (Z) +/-	
7	A Horizontal longitudinal (Y)		
8	B Horizontal longitudinal (Y)		
9	C Horizontal longitudinal (Y)		
10	D Horizontal longitudinal (Y) +/-		
11	C Horizontal transversal (X)		
12	D	Horizontal transversal (X) +/-	

#### 2.3. Mounting and orientation of the test item

For tests A to D, the test item was fixed to the test surface by clamping the flat metal base of the shock damper base inside a transport frame directly onto the test surface. Transport wheels were removed to improve the transfer of test energy through the test item and create a worst case transportation scenario. The test item was mounted on the vibration table in the normal orientation with respect to the vertical. The tests were carried out in three mutually perpendicular directions, see Figure #3 for the vertical (Z) direction, see Figure #4 for the horizontal transversal (X) direction and see Figure #5 for the horizontal longitudinal (Y) direction.

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Apparatus and/or instrumentation	Supplier	Model Number	Serial Number	Last / Nex Calibra Verificatio Inspec	t date of ation, n and/or ction
Monitoring of the environmental conditions	E+E Elektronik	HUMOLOG20 THIP	056.0420. 0802.034	02/04/24	02/04/26
Weighing instrument	Stimag B.V.	STL-H/ESP20	28199	10/06/24	10/06/26
Electric-dynamic shaker	Tira	TV 59355/AIT- 440 TGT Model 48XXL	036/07	20/06/23	20/06/25
Shaker control system	Dactron	Laser	8969761	09/08/24	09/08/25
Signal Conditioner	PCB Piezotronics	482C16	428	11/08/23	11/08/25
ICP Accelerometer (reference/check point)	PCB Piezotronics	353B34	LW235695	25/04/24	25/04/25
ICP Accelerometer (reference/check point)	PCB Piezotronics	353B34	LW235696	25/04/24	25/04/25
ICP Accelerometer (response point)	PCB Piezotronics	352C22	LW341978	25/10/24	25/10/25
ICP Accelerometer (reference/check point)	PCB Piezotronics	353B18	149911	10/07/24	10/07/25

### 2.4. Description of the used apparatus and instrumentation

### 2.5. Sketch of the test A - D configuration



### 2.6. Measurement uncertainty and tolerances

All the measurements were carried out with a signal tolerance includes instrumentation errors lower than 5% according to the standards. The combined standard uncertainly and the expanded uncertainty (k=2) *U* is lower than 10% according. Measurement Uncertainty Calculator form version 25.7. For lower vibration frequency (>1 <10Hz), large size and high mass the signal tolerance is lower than 10%. Temperature and relative humidity are not operational factors.

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### 3. Random vibration and terminal peak sawtooth shock tests

### 3.1. General

The vibration and shock tests were carried out in three mutually perpendicular directions on a shaker.

### 3.1.1. Test A to C: Random vibration test setup

The vibration tolerance bands at the reference point is within  $\pm 3$ dB. The initial slope is less than  $\pm 6$ dB/octave and the final slope is -24dB/octave. The used frequency range of the measuring system is 0,5 times the low frequency and 2 times the highest frequency. The frequency response is flat within  $\pm 5\%$  over the test frequency range. The cross-axis motion and the vibration response (investigation) measurements were not carried out. See Table 3 for the used vibration parameters.

able e. Randelli vibration control parametere			
System	Parameters		
Controller	Closed loop – Automatic Equalization		
Number of Spectral Lines:	800		
Max. Test Frequency:	500.00 Hz		
Measurement Strategy:	Weighted Average		
Line Abort Ratio:	0.30		
Line Abort Number:	240		
Averaging Number:	77		
Drive Limit:	10.00 Volts		
Sigma Clip Number:	5.00		
Data Points/Frame:	2048		
Frame Time:	1.600000 Seconds		
Sampling Rate:	1280 Hz		
DOF:	154		
dT:	0.000781 Seconds		
dF:	0.625000 Hz		

Table 3: Random vibration control parameters

### 3.1.2. Test D: Shock test setup

The used peak acceleration tolerance is 0,8 and 1,2 times for the half-sine shock test. The effects of gravity will be considered when considering the altitude of the test. The minimum monitored pulse time for the produced shocks is 6x duration of the nominal pulse. The positive and/or negative peak acceleration at the check point(s), perpendicular to the intended shock direction, does not exceed 30 % of the value of the peak acceleration of the nominal pulse in the intended direction. See Table 5 for the used shock parameters.

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Table 4: Shock control parameters

System	Parameters
Controller	Closed loop – Automatic Equalization
Block Size:	Auto
Averaging Number:	4
Drive Limit:	10.00 Volts
Pulse Interval:	10.000 seconds
Point Abort Ratio:	0.10
Low-Pass Filter Type:	Apply filter using user-defined cutoff frequency
Filter Cutoff Frequency:	800.00000Hz
Data Points/Frame:	8192
Frame Time:	0.682667 Seconds
Sampling Rate:	12000 Hz
dT:	8.33333e-005 Seconds
Maximum Analysis Frequency:	5273.44 Hz
SRS Analysis:	Enable
SRS Analysis Low Frequency Bound:	1.00000Hz
SRS Analysis High Frequency Bound:	1000.000000Hz
SRS Analysis Reference Frequency:	100.00000Hz
SRS Analysis Damping Ratio:	0.050000
SRS Analysis Fractional Octave Number:	1/3

### 3.1.3. Accelerometers location and orientation

See Table 5 for the location and orientation of the used accelerometers during the tests.

	able 5. Used acceleronieters					
Test item	Direction	Channel	Accelerometer Serial number	celerometer rial number		
1	XYZ	1	LW235695	LW235695 On table, front left		
1	XYZ	2	LW235696	-W235696 On table, rear right		
1	XYZ	3	LW341978	1978 On test item		
1	XYZ	4	149911	On shock damper base	#3 - #5	

Table 5: Used accelerometers

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### 3.2. Test Results

### 3.2.1. Test A: Random vibration test result (Sea)

One test item has been used for the random vibration test which was carried out in the three mutually perpendicular directions, see Table 6 for the result summary. See Figure #6 for a typical vibration plot and Figure #7 to #9 for the transmissibility measurements of accelerometer response channels 3 and 4. The natural frequency (Fn) of the test item was identified at 8-9Hz, damping started to occur at 12Hz. No visual damage or functional errors were found on the test item after the complete test sequence.

#### Table 6: Random vibration test result summary

Test item	Direction	Test time [min]	Remarks*
1	Horizontal transversal (X)	60	Pass
1	Vertical (Z)	60	Pass
1	Horizontal longitudinal (Y)	60	Pass

\*Pass and fail remarks refer only to the ability of the test item to complete the test sequence.

### 3.2.2. Test B: Random vibration test result (Rail)

One test item has been used for the random vibration test which was carried out in the three mutually perpendicular directions, see Table 7 for the result summary. See Figure #10 for a typical vibration plot. See Figure #11 to #13 for the transmissibility measurements of accelerometer response channels 3 and 4. The natural frequency (Fn) of the test item was identified at 7Hz, damping started to occur at 10Hz. No visual damage or functional errors were found on the test item after the complete test sequence.

### Table 7: Random vibration test result summary

Test item	Direction	Test time [min]	Remarks*
1	Horizontal transversal (X)	60	Pass
1	Vertical (Z)	60	Pass
1	Horizontal longitudinal (Y)	60	Pass

\*Pass and fail remarks refer only to the ability of the test item to complete the test sequence.

### 3.2.3. Test C: Random vibration test result (Common carrier)

One test item has been used for the random vibration test which was carried out in the three mutually perpendicular directions, see Table 8 for the result summary. See Figure #14 for a typical vibration plot, see Figure #15 to #17 for the transmissibility measurements of accelerometer response channels 3 and 4. The natural frequency (Fn) of the test item was identified at 6Hz, damping started to at 8,5Hz. No visual damage or functional errors were found on the test item after the complete test sequence.

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Test item	Direction	Test time [min]	Remarks*
1	Vertical (Z)	60	Pass
1	Horizontal longitudinal (Y)	60	Pass
1	Horizontal transversal (X)	60	Pass

#### Table 8: Random vibration test result summary

\*Pass and fail remarks refer only to the ability of the test item to complete the test sequence.

#### 3.2.3. Test D: Terminal peak sawtooth shock test result

One test item has been used for the terminal peak sawtooth shock test which was carried out in the three mutually perpendicular ( $\pm$ ) directions, see Table 9A – 9C for the result summary. See Figure #18 for a typical shock plot. See Figure #19 to #24 for the shock response measurements of accelerometer inputs 3 and 4 during the shocks with the highest intensity. For shock number 12, the input shock value was 15,2g. The maximum amplitude measured by the response sensor placed on the back of the display was 1g in the vertical, 1g in the longitudinal and 1,5g in the transversal thereby reducing the shock by between 90% to 93%. No visual damage or functional errors were found on the test item after the complete test sequence.

Test no	Direction	Amplitude [g]	Pulse duration [ms]	No of shocks	Remarks*	
1	Vertical (Z-)	5,1	11	42	Pass	
2	Vertical (Z+)	5,1	11	42	Pass	
3	Vertical (Z-)	6,4	11	21	Pass	
4	Vertical (Z+)	6,4	11	21	Pass	
5	Vertical (Z-)	7,6	11	3	Pass	
6	Vertical (Z+)	7,6	11	3	Pass	
7	Vertical (Z-)	10,2	5	42	Pass	
8	Vertical (Z+)	10,2	5	42	Pass	
9	Vertical (Z-)	12,8	5	21	Pass	
10	Vertical (Z+)	12,8	5	21	Pass	
11	Vertical (Z-)	15,2	5	3	Pass	
12	Vertical (Z+)	15,2	5	3	Pass	

Table 9A: Shock test result summary vertical (Z) direction

\*Pass and fail remarks refer only to the ability of the test item to complete the test sequence.

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$\Lambda$	
- \ \ \ \ \ \ -	

Test item	Direction	Direction Amplitude Pulse No of [g] [ms]		Remarks*	
1	Longitudinal (Y-)	5,1	11	42	Pass
1	Longitudinal (Y+)	5,1	11	42	Pass
1	Longitudinal (Y-)	6,4	11	21	Pass
1	Longitudinal (Y+)	6,4	11	21	Pass
1	Longitudinal (Y-)	7,6	11	3	Pass
1	Longitudinal (Y+)	7,6	11	3	Pass
1	Longitudinal (Y-)	10,2	5	42	Pass
1	Longitudinal (Y+)	10,2	5	42	Pass
1	Longitudinal (Y-)	12,8	5	21	Pass
1	Longitudinal (Y+)	12,8	5	21	Pass
1	Longitudinal (Y-)	15,2	5	3	Pass
1	Longitudinal (Y+)	15,2	5	3	Pass

Table 9B: Shock test result summary horizontal longitudinal (Y) direction

\*Pass and fail remarks refer only to the ability of the test item to complete the test sequence.

Test item	Direction	Amplitude [g]	Pulse duration [ms]	No of shocks	Remarks*
1	Transversal (X-)	5,1	11	42	Pass
1	Transversal (X+)	5,1	11	42	Pass
1	Transversal (X-)	6,4	11	21	Pass
1	Transversal (X+)	6,4	11	21	Pass
1	Transversal (X-)	7,6	11	3	Pass
1	Transversal (X+)	7,6	11	3	Pass
1	Transversal (X-)	10,2	5	42	Pass
1	Transversal (X+)	10,2	5	42	Pass
1	Transversal (X-)	12,8	5	21	Pass
1	Transversal (X+)	12,8	5	21	Pass
1	Transversal (X-)	15,2	5	3	Pass
1	Transversal (X+)	15,2	5	3	Pass

\*Pass and fail remarks refer only to the ability of the test item to complete the test sequence.

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### 3.3. Final inspection

After the complete test sequence, a visual inspection has been carried out on the test item. See Table 10 for the inspection results.

Table 10: Visual inspection results

Test item	Results and/or remarks	Figure
#1	After all testing had been completed, the display was able to be powered on without error. The display was also able to be raised and lowered by the motorized extendable feet without error.	#25 #29

One Display Solution will carry out the final inspection and report the results after the completed test sequence.

#### 3.4. Laboratory ambient (during test)

See Figure #30 for the environmental measurements during the test sequence.

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### 4. Conclusion and remarks

One test item has been subjected to vibration and shock tests according to the normative documents:

- Department of Defense Test Method Standard Environmental Engineering Considerations and Laboratory Tests – MIL-STD-810H: 2019
  - NATO Standard AECTP-400 Mechanical Environment Tests Edition D Version 1 November 2019 - method 401. (Vibration)
  - NATO Standard AECTP-400 Mechanical Environment Tests Edition D Version 1 November 2019 - method 403. (Shock)

See the following table for the summary of the test results:

Test A: Random vibration test Material Transported by Sea	During the random vibration test, the test item was not functional. No visual damage or functional errors were found on the test item after the complete test. This result validates the test items ability to endure sea transportation of 9 months
Test B: Random vibration test Material Transported by Rail	During the random vibration test, the test item was not functional. No visual damage or functional errors were found on the test item after the complete test. This result validates the test items ability to endure rail transportation of 30.000km
Test C: Random vibration test Common carrier	During the random vibration test, the test item was not functional. No visual damage or functional errors were found on the test item after the complete test. This result validates the test items ability to endure transportation by wheeled vehicles predominantly on improved roads by common carrier for 4800km
Test D: Terminal peak sawtooth shock test	During the shock test, the test item was not functional. No visual damage or functional errors were found on the test item after the complete test. This result validates the test items ability to endure the shocks encountered during transportation by road over 5000km and by off-road over 1000km

One Display Solution will carry out the final inspection on the test item after the completed test sequence.

Approved by M.J.H. Magendans Director Fest Specialist

Testing carried out by R. Morris

Test Lab Manager

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#### Figures

#### Figure 1: Test item



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Figure 3: Test direction vertical (Z) and accelerometer location

Figure 4: Test direction horizontal transversal (X) and accelerometer location



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Figure 7: Test A Sea - Transmissibility measurement, input 3 and 4 transversal X





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Figure 9: Test A Sea - Transmissibility measurement, input 3 and 4 longitudinal Y



Figure 10: A typical random vibration rail transport simulation PSD plot

Control RMS: 0.689777 gn Full Level Elapsed Time: 01:00:03 0.689019 gn Remaining Time: Demand RMS: 00:00:00 DOF: 154 dF:

0.312500 Hz

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Figure 15: Test C - C.Carrier Transmissibility measurement, input 3 and 4 vertical Z





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Figure 17: Test C - C.Carrier Transmissibility measurement, input 3 and 4 transversal X





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Figure 19: A typical terminal saw tooth shock plot vertical (Z) 7,6g @ 11ms





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Figure 21: A typical terminal saw tooth shock plot longitudinal (Y) 7,6g @ 11ms



0.04

Time (Seconds)



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0.01

0.02

0.03

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0.05

0.06

0.07

0.08

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6.0000 4.5000 3.0000 1.5000 0 -1.5000 -3.0000 -4.2000 -0.00 0

> Chamber of Commerce: 24346465 VAT no: NL8121.08.553.B01 Bank no. NL95ABNA0.50.13.23.465 Swift: ABNANL2A Statutory Director: M.J.H. Magendans **RvA accreditation No: L540**







Figure 23: A typical terminal saw tooth shock plot transversal (X) 7,6g @ 11ms





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Figure 27: Final inspection



Figure 28: Final inspection



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Figure 29: Final inspection



#### Figure 30: Laboratory ambient conditions during testing

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Minimum         19,8         16,4         1018,5           Maximum         28,1         35,7         1028,8           Standard Deviation         1,9         3,8         3,2           Variance         3,8         14,7         10,5	Average	22,3	24,7		1023,9								
Maximum         28,1         35,7         1028,8           Standard Deviation         1,9         3,8         3,2           Variance         3,8         14,7         10,5	Minimum	19,8	16,4		1018,5								
Standard Deviation         1,9         3,8         3,2           Variance         3,8         14,7         10,5	Maximum	28,1	35,7		1028,8								
Variance 3.8 14,7 10,5	Standard Deviation	1,9	3,8		3,2								
	Variance	3,8	14,7		10,5								

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#### Abbreviations

Acc	Acceleration
ASD	Acceleration Spectral Density
AvC	Average Control
dB	decibel
DOF	Degrees of Freedom
Drive	Voltage output of the controller used to drive the shaker
DUT	Device under test
Dwell	Endurance test on 'fixed' frequency
Fail	Criteria if the DUT is tested outside the described TS of the normative doc
Fn	Natural frequency
g	Acceleration due to gravity (equal to 9,81 m/s <sup>2</sup> )
Hz	Hertz
IFC	Information from customer
kg	Kilogram
Manuf	Manufacturer
ms	Milliseconds, nominal duration
Ν	Newton (force)
Oct/min.	Sweep rate
Oper	Operational
Ра	Pressure
Pass	Criteria if the DUT is tested as described in the TS of the required normative doc
PK	Peak
PK-PK	Peak to Peak
PSD	Power Spectral Density
Q	Quality, Sharpness measure of a resonance
Res	Resonance
RS	Resonance Survey
RMS	Root Mean Square
Seq	Sequence
S/N	Serial Number
SRS	Shock Response Spectrum
Sweep	One sweep up or down
TS	Test Specification
V	Voltage

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ILAC stands for International Laboratory Accreditation Cooperation. The European Union (EU) has entered into mutual recognition agreements (MRAs) with various countries. This means that the countries have to accept each other's products. The technical aspect of the ISO/IEC 17025 standard relates to the use of qualified and experienced staff. All test equipment in our Sebert Trillingstechniek laboratory has been calibrated and checked in accordance with the ISO/IEC 17025 standard. This ensures that the tests, obtained in an independent, professional and objective manner, are extremely reliable

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#### Distribution

Report	M25.001-P25.001 one display solution
Title	MIL-STD 810/AECTP 400 Random Vibration and Terminal Peak Sawtooth Shock Tests on a PSM-P86RV1
Institute	Sebert Trillingstechniek B.V at Bergschenhoek in The Netherlands

Company: one display solution Mr. S. van Tongeren Number of copies 1

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